

# Development of versatile online monitoring for EUDAQ2

Andreas Loeschke Centeno

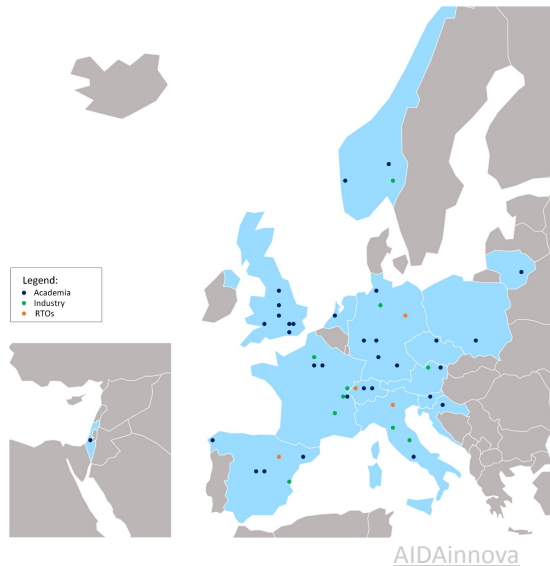
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Fabrizio Salvatore, Lennart Huth ([lennart.huth@desy.de](mailto:lennart.huth@desy.de))



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 101004761.

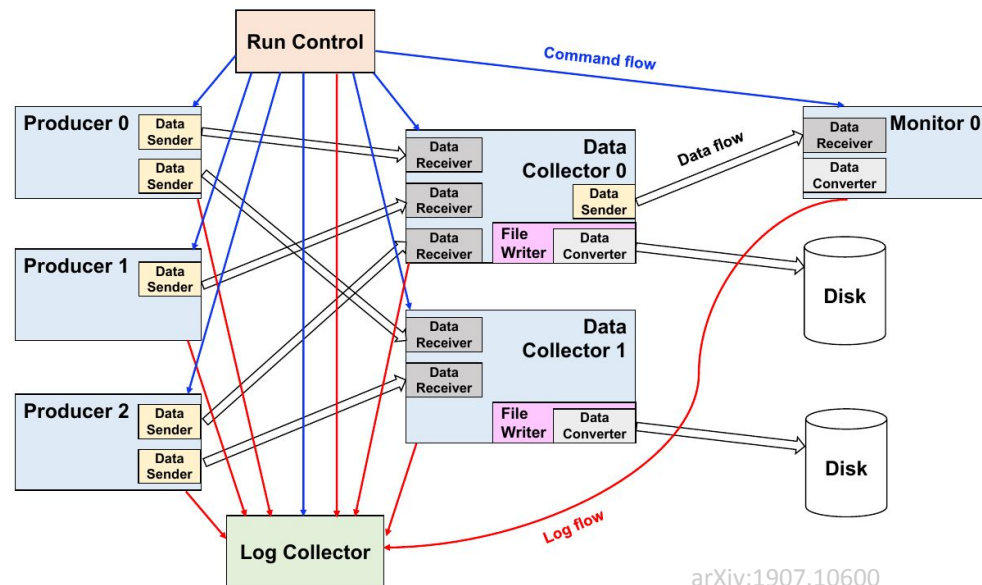
- 4 year programme (30 M€ Budget)
- Development of common detector projects
- Upgrades to research infrastructure
- 42 participants from 15 countries

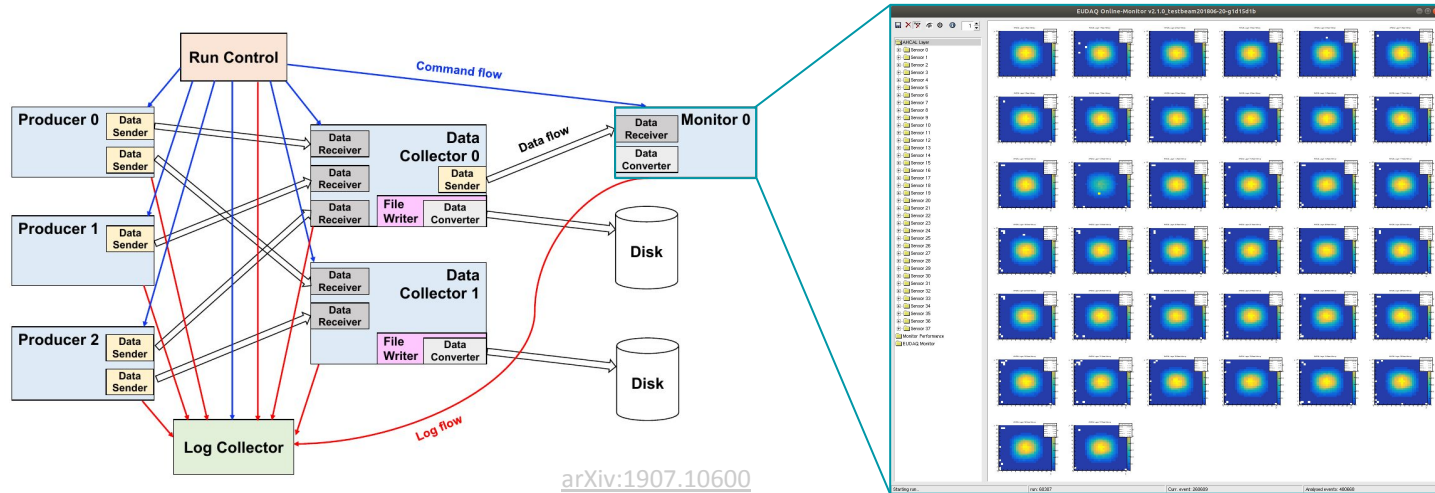


### WP 3: Test beam and DAQ infrastructure

- Development of common test beam resources (hardware & software)
- Task 3.4: Development of versatile online monitoring for EUDAQ2
  - Objective: release monitoring tool usable by any test beam user with any kind of detector

- Data Acquisition Control System
  - Provides central DAQ control, data handling and storage, log collection
  - Distributes all commands among all modules
- Architecture based on runtime-instances
  - Producer is interface between custom DAQ for DUT and EUDAQ2
  - DataCollector for merging/synchronising data
  - DataConverter from raw data to StdEvent

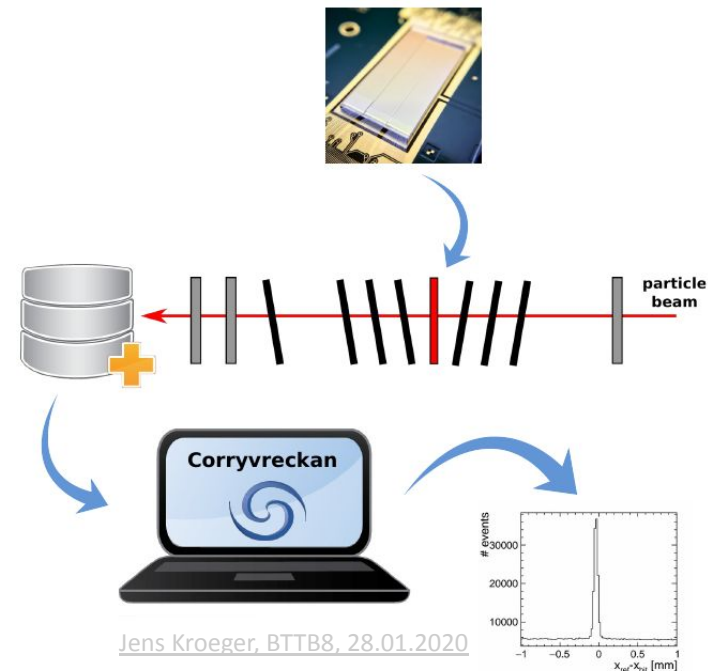




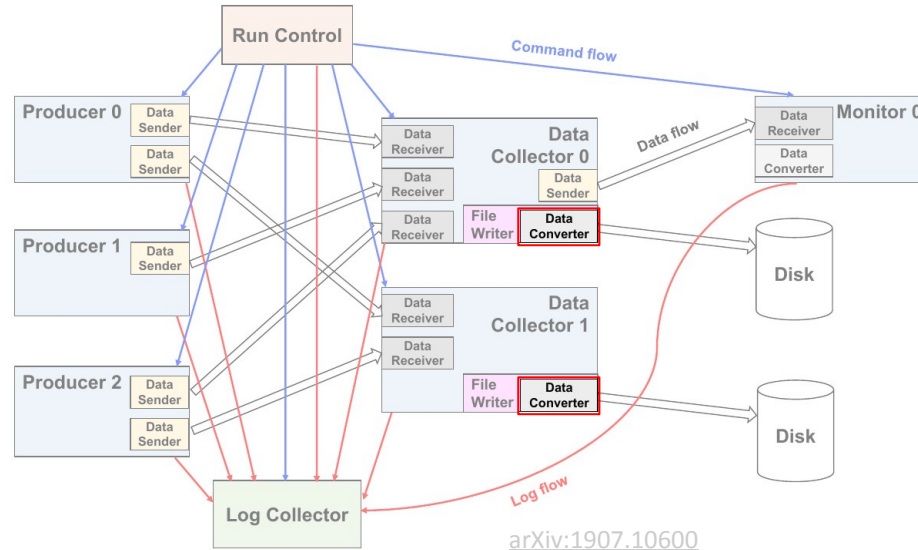
- No flexible event building
- No information about detector geometry
- No advanced reconstruction
- But widely used software [corrvreckan](#) provides everything we need
  - Idea: Combine [corrvreckan](#) with EUDAQ2 for monitoring

- Widely used track reconstruction and analysis software for test beam data
- Developed by pixel community, but not limited to pixel sensors
- Versatile, highly configurable with modular structure
  - Lightweight framework core
  - Modules for specific tasks, e.g.:
    - ◆ Event Loading
    - ◆ Clustering
    - ◆ Tracking
    - ◆ Offline alignment
- Graphical user interface for monitoring of reconstruction progress
- Modern C++, minimal external dependencies
- Extensive [documentation](#)

[BTTB12](#)  
[Corryvreckan](#)  
[Tutorial](#)



- Direct compatibility with EUDAQ2
  - Load EUDAQ2 raw events via EventLoaderEUDAQ2 module
  - Requires eudaq::StdEventConverter



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  - Nomenclature for pixels, but can be used generically
  - Mapping to pixels and planes done in StdEventConverter

## Geometry file

```
[my_ex0_plane_0]
number_of_pixels = 16, 16
orientation = 0deg,0deg,0deg
orientation_mode = "xyz"
pixel_pitch = 55um,55um
position = 0um,0um,0um
role = "dut", "reference"
time_resolution = -1ns
type = "ex0raw"
```

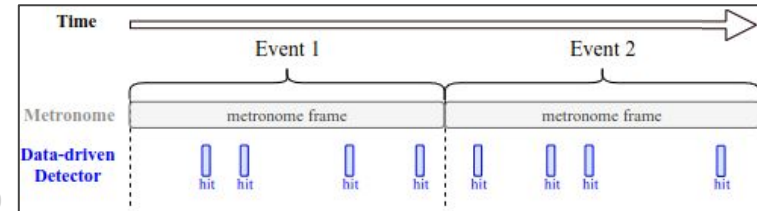
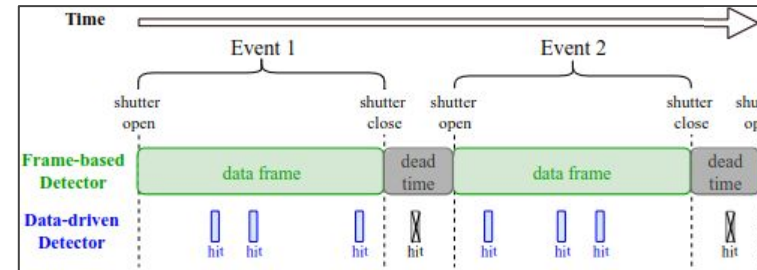
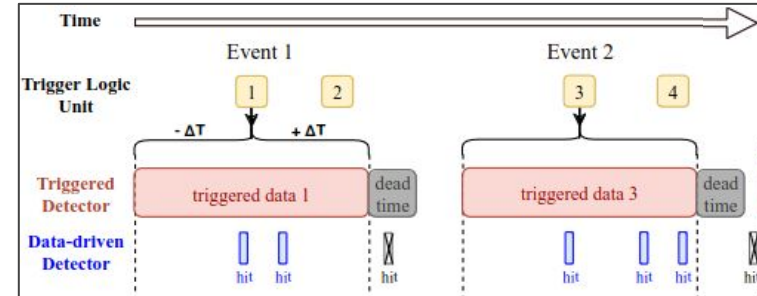
## Example eudaq::RawEvent2StdEventConverter

```
bool Ex0RawEvent2StdEventConverter::Converting(eudaq::EventSPC d1, eudaq::S
auto ev = std::dynamic_pointer_cast<const eudaq::RawEvent>(d1);
size_t nblocks= ev->NumBlocks();
auto block_n_list = ev->GetBlockNumList();
for(auto &block_n: block_n_list){
    std::vector<uint8_t> block = ev->GetBlock(block_n);
    if(block.size() < 2)
        EUDAQ_THROW("Unknown data");
    uint8_t x_pixel = block[0];
    uint8_t y_pixel = block[1];
    std::vector<uint8_t> hit(block.begin()+2, block.end());
    if(hit.size() != x_pixel*y_pixel)
        EUDAQ_THROW("Unknown data");
    eudaq::StandardPlane plane(block_n, "my_ex0_plane", "my_ex0_plane");
    plane.SetSizeZS(hit.size(), 1, 0);
    for(size_t i = 0; i < y_pixel; ++i) {
        for(size_t n = 0; n < x_pixel; ++n){
            plane.PushPixel(n, i, hit[n+i*x_pixel]);
        }
    }
    d2->AddPlane(plane);
}
return true;
}
```



# Corryvreckan: A Perfect Candidate

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  - Nomenclature for pixels, but can be used generically
  - Mapping to pixels and planes done in StdEventConverter
- Flexible event building
  - Trigger-based, frame-based, data-driven

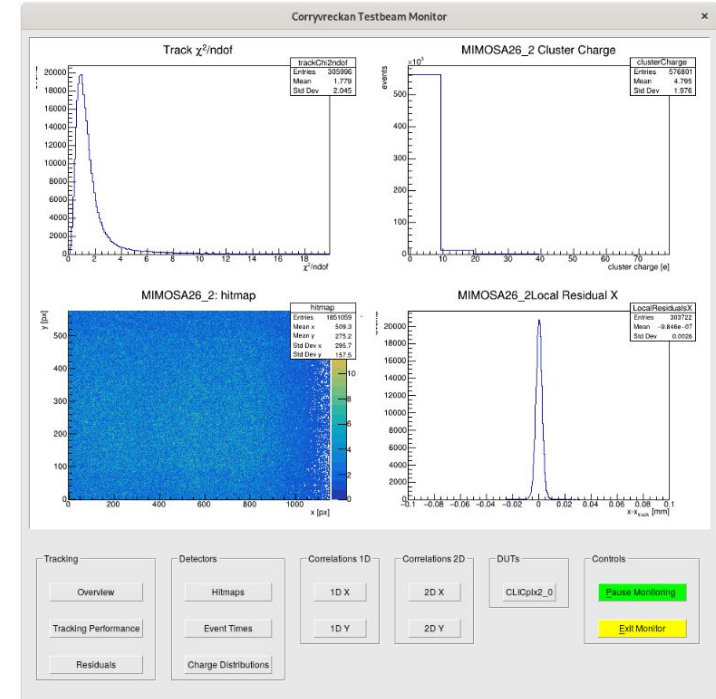


arXiv:2011.12730



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- Monitoring of reconstruction chain (event loading, clustering, tracking)



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- Flexible event building
  - Trigger-based, frame-based, data-driven
- Monitoring of reconstruction chain (event loading, clustering, tracking)
- Only need to figure out how to seamlessly integrate into EUDAQ2:  
**CorryMonitor**



[Lennart Huth, AIDAinnova](#)  
[2nd Annual Meeting.](#)  
[27.04.2023](#)

Maximise user convenience (while maintaining flexibility):

- Fully integrated into EUDAQ2
  - Start and stop from RunControl
- Require minimal user input to get monitoring running
- Corryvreckan only capable of *semi*-online monitoring
  - Events not sent directly but read from file
    - Automatically finds correct files to monitor and pass on start-up
- Able to read files on different machines

## 1. Startup

```
#!/usr/bin/env sh
BINPATH=../../bin
$BINPATH/euRun &
sleep 1
$BINPATH/euLog &
sleep 1
$BINPATH/euCliMonitor -n CorryMonitor -t my_mon &
$BINPATH/euCliCollector -n Ex0TgDataCollector -t my_dc0 &
$BINPATH/euCliProducer -n Ex0Producer -t my_pd0 &
```

## 2. EUDAQ2 .ini file

```
[Monitor.my_mon]
CORRY_PATH = /path/to/bin/corry #executable
```

## 3. EUDAQ2 .conf file

```
[Monitor.my_mon]
CORRY_CONFIG_PATH=./corryconfig.conf
CORRY_OPTIONS=-v INFO
DATACOLLECTORS_TO_MONITOR = my_dc0
CORRESPONDING_EVENTLOADER_TYPES = Ex0raw
```

### corryvreckan .conf file

```
[Corryvreckan]
detectors_file = "corrygeo.geo"
detectors_file_updated = "corrygeo_updated.geo"
histogram_file = "corry_histo_file_example.root"
```

```
[Metronome]
triggers = 1
event_length = 1s
```

```
[EventLoaderEUDAQ2]
type = "Ex0Raw"
eudaq_loglevel=INFO
buffer_depth=5
inclusive=1
```

```
[OnlineMonitor]
dut_plots = [{"EventLoaderEUDAQ2/%DUT%/hRawValuesMap", "colz"},
             [{"EventLoaderEUDAQ2/%DUT%/hPixelRawValues", "log"}]]
hitmaps = [{"EventLoaderEUDAQ2/%DUT%/hRawValuesMap", "colz"}]
```

### corrygeo.geo

```
[my_ex0_plane_0]
number_of_pixels = 16, 16
orientation = 0deg,0deg,0deg
orientation_mode = "xyz"
pixel_pitch = 55um,55um
position = 0um,0um,0um
role = "dut","reference"
time_resolution = -1ns
type = "ex0raw"
```

```
[my_ex0_plane_1]
number_of_pixels = 16, 16
orientation = 0deg,0deg,0deg
orientation_mode = "xyz"
pixel_pitch = 55um,55um
position = 0um,0um, 50m
role = "dut"
time_resolution = -1ns
type = "ex0raw"
```

Level: From: Search:

O-DEBUG All

Received	Sent	Level	Text
08:01:09.123	08:01:09.123	4-INFO	Processing StartRun command for RUN #1065
08:01:09.223	08:01:09.223	4-INFO	RUN #1065 is to be started...
08:01:09.224	08:01:09.224	0-DEB...	File string for matching is dc0_run1065_*.raw
08:01:09.225	08:01:09.225	4-INFO	RUN #1065 is started.
08:01:10.324	08:01:10.324	4-INFO	RUN #1065 is to be started...
08:01:10.325	08:01:10.325	4-INFO	DataReceiver: Connection from <Connection>
08:01:10.326	08:01:10.326	4-INFO	RUN #1065 is started.
08:01:12.424	08:01:12.424	4-INFO	RUN #1065 is to be started...
08:01:12.427	08:01:12.427	0-DEB...	The file config_run_1065.txt was created
08:01:12.428	08:01:12.427	0-DEB...	Testing pattern dc0_run1065_*.raw
08:01:12.428	08:01:12.428	4-INFO	DataReceiver: Connection from <Connection>
08:01:12.428	08:01:12.428	4-INFO	RUN #1065 is started.
08:01:12.429	08:01:12.428	0-DEB...	The file dc0_run1065_240329080112.raw was
08:01:12.429	08:01:12.429	0-DEB...	Testing pattern dc0_run1065_*.raw
08:01:12.429	08:01:12.429	0-DEB...	Found a match with pattern dc0_run1065_*.r
08:01:12.429	08:01:12.429	4-INFO	Found file /home/andreas/Documents/eudaq
08:01:12.429	08:01:12.429	0-DEB...	Full command passed to execvp calling corry

```

[08:01:13.905] (WARNING) [I:OnlineMonitor] Histogram /Correlations/
[08:01:13.905] (WARNING) [I:OnlineMonitor] Histogram /Tracking4D/my
[08:01:13.905] (INFO) [I:OnlineMonitor] Connecting button with cd
[08:01:13.909] (WARNING) [I:OnlineMonitor] Histogram /Tracking4D/trf
[08:01:13.909] (WARNING) [I:OnlineMonitor] Histogram /Tracking4D/trf
[08:01:13.909] (WARNING) [I:OnlineMonitor] Histogram /Tracking4D/trf
[08:01:13.909] (WARNING) [I:OnlineMonitor] Histogram /Tracking4D/trf
[08:01:13.910] (WARNING) [I:OnlineMonitor] Histogram /Tracking4D/trf
[08:01:13.910] (WARNING) [I:OnlineMonitor] Histogram /Tracking4D/clu
[08:01:13.910] (INFO) [I:OnlineMonitor] Connecting button with cd
[08:01:13.914] (INFO) [I:OnlineMonitor] Connecting button with cd
[08:01:13.918] (INFO) [I:OnlineMonitor] Connecting button with cd
[08:01:13.921] (WARNING) [I:OnlineMonitor] Histogram /Correlations/
[08:01:13.921] (INFO) [I:OnlineMonitor] Connecting button with cd
[08:01:13.925] (WARNING) [I:OnlineMonitor] Histogram /ClusterInq4D/
[08:01:13.925] (INFO) [I:OnlineMonitor] Connecting button with cd
[08:01:13.929] (WARNING) [I:OnlineMonitor] Histogram /Correlations/
[08:01:13.930] (INFO) [I:OnlineMonitor] Connecting button with cd
[08:01:13.933] (WARNING) [I:OnlineMonitor] Histogram /Correlations/
[08:01:13.934] (INFO) [I:OnlineMonitor] Connecting button with cd
[08:01:13.937] (WARNING) [I:OnlineMonitor] Histogram /Correlations/
[08:01:13.937] (INFO) [I:OnlineMonitor] Connecting button with cd
[08:01:13.941] (WARNING) [I:OnlineMonitor] Histogram /Correlations/
[08:01:13.941] (INFO) [I:OnlineMonitor] Connecting button with cd
[08:01:13.993] (WARNING) [I:OnlineMonitor] Histogram /ClusterInq4D/
[08:01:13.993] (STATUS) [I:OnlineMonitor] Event loop [
[08:01:14.496] (STATUS) Ev: 1.9k Px: 485.9k Tr: 0.8k (0/ev) t = 188
[08:01:14.498] (INFO) [R:EventLoaderEUDAQ2:my_ex0_plane_0] Waitin
[08:01:15.006] (STATUS) Ev: 3.1k Px: 792.8k Tr: 0.8k (0/ev) t = 398
[08:01:15.007] (INFO) [R:EventLoaderEUDAQ2:my_ex0_plane_0] Waitin
[08:01:17.109] (STATUS) Ev: 4.3k Px: 1.16M Tr: 0.8k (0/ev) t = 429
[08:01:17.112] (INFO) [R:EventLoaderEUDAQ2:my_ex0_plane_0] Waitin
[08:01:19.507] (STATUS) Ev: 6.2k Px: 1.59M Tr: 0.8k (0/ev) t = 619
    
```

Current State: Running

State: Control

Init file: /home/andreas/Documents/eudaq/user/example/misc/CorryMon.ini

Control: Load Init Config Stop Terminate Log Configs Start Scan

Corryrekan Testbeam Monitor

rawValues

rawValues

Tracking

Overview

Tracking Performance

Residuals

Detectors

Hitmaps

Event Times

Charge Distributions

Correlations 1D

1D X 2D X

1D Y 2D Y

DUTs

my\_ex0\_plane\_0

my\_ex1\_plane\_0

Controls

Pause Monitoring

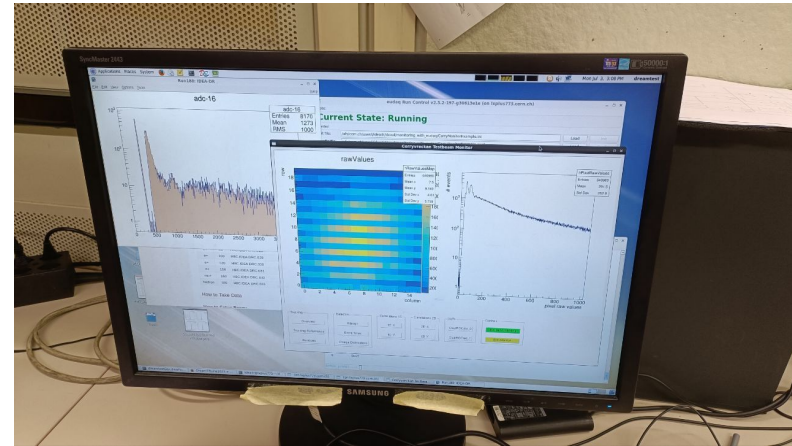
Exit Monitor



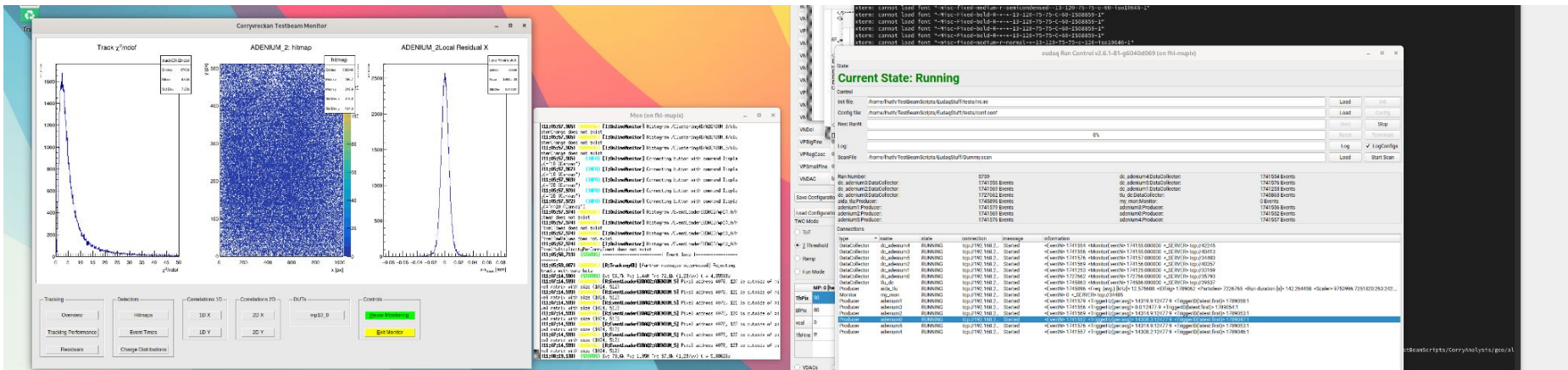
- Dual-readout EM prototype
  - 160 Scintillation, 160 Cherenkov fibres individually read out by SiPMs
  - No longitudinal segmentation, i.e. no “layers”
  - But could define Scintillation and Cherenkov channels as own layers or high gain and low gain



courtesy: [INFN-PV Lab](#)



# TelePix2 + ALPIDE Telescope Monitoring



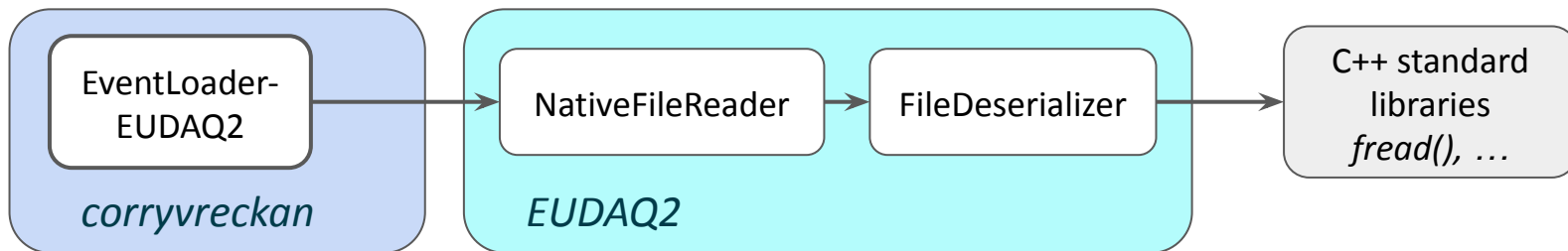
courtesy: Lennart Huth

- TelePix2 beam test with ALPIDE telescope at DESY by Lennart Huth et. al.
- Beam telescope allows to fully exploit corryvreckan functionality (correlations, tracking)

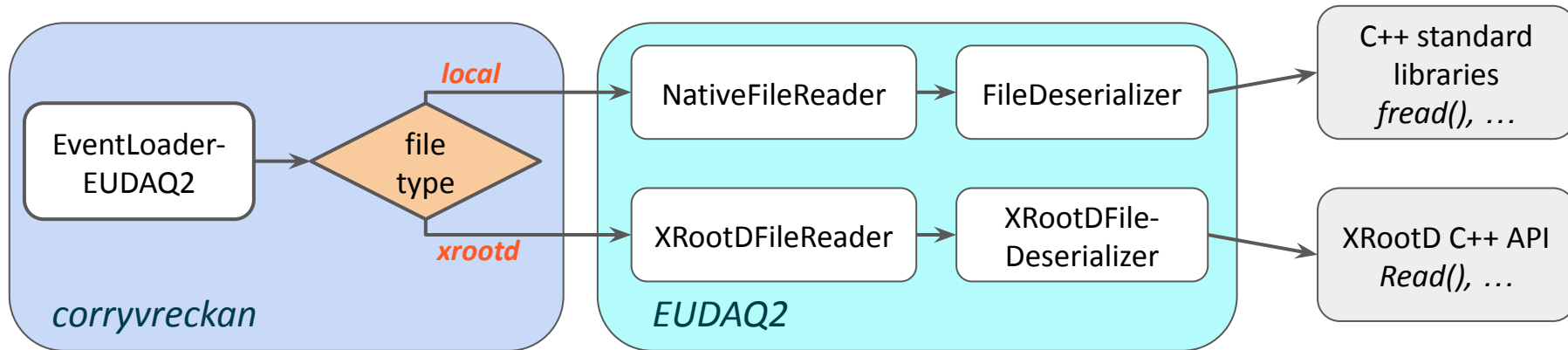




- Want to be able to **monitor DataCollectors on different machine**
- Copying files over is not an option
- Need quick way to establish connection
- [XRootD](#) software offers solution
  - Allows fast, low latency and scalable data access
- Need to make EUDAQ2 and corryvreckan compatible with XRootD



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- XRootD software offers solution
  - Allows fast, low latency and scalable data access
- Need to make EUDAQ2 and corryvreckan compatible with XRootD



- User needs to start XRootD server/ensure connection
- In the .conf file pass server addresses in order (remote DataCollectors first, then local)

```
[Monitor.my_mon]
CORRY_CONFIG_PATH=corryconfig.conf
CORRY_OPTIONS=-v INFO
DATACOLLECTORS_TO_MONITOR = my_xrootd_dc0, my_xrootd_dc1, my_local_dc0
CORRESPONDING_EVENTLOADER_TYPES = Ex0raw, Ex1raw, Ex2raw
XROOTD_ADDRESSES = server0name@127.0.0.1:51234, server1name@127.0.0.1:54321
                   xrootd      IP address  port
                   server-name
```

- Tested in lab setting
- Unfortunately no opportunity to test in test beam setting so far

- Goal: versatile online monitoring tool usable by any test beam users
- Corryvreckan provides underlying functionality
  - Much comes for free
- Well integrated into EUDAQ2
- Have had / will have some testing opportunities
  - Reading files on different machines at test beam would be nice
- Planning to release into eudaq (and corryvreckan) repositories soon



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 101004761.

**Thank you for your Attention!**

```
case 0: // child: start carryvreckan
```

```
fd = inotify_init();  
if ( fd < 0 ) {  
    perror( "Couldn't initialize inotify");  
}  
  
wd = inotify_add_watch(fd, monitor_file_path.c_str(), IN_CREATE);
```

```
while(waiting_for_matching_file){
```

```
int length, i = 0;  
char buffer[BUF_LEN];
```

```
length = read( fd, buffer, BUF_LEN );  
if ( length < 0 ) {  
    perror( "read" );  
}
```

```
while ( i < length ) {  
    struct inotify_event *event = ( struct inotify_event * ) &buffer[ i ];  
  
    if ( event->mask & IN_CREATE ) { // if event is a creation of object in directory  
        if ( !(event->mask & IN_ISDIR) ) { // if object created is a file  
            if ( event->len ) { // if filename is not empty  
                std::stringstream ss;  
                ss << event->name;  
                event_name = ss.str();  
  
                EUDAQ_DEBUG("The file " + event_name + " was created");  
                EUDAQ_DEBUG("Pattern to match is " + pattern_to_match);  
  
                if (string_match(pattern_to_match.c_str(), event_name.c_str(), 0, 0))  
                    waiting_for_matching_file = false;  
            }  
        }  
    }  
  
    i += EVENT_SIZE + event->len;  
}
```

```
EUDAQ_INFO("File to be monitored is "+monitor_file_path+event_name);
```

```
#include <sys/wait.h>  
#include <sys/stat.h>  
#include <sys/inotify.h>  
#include <regex>  
#include <filesystem>
```

Fork to start carry

Setting up inotify

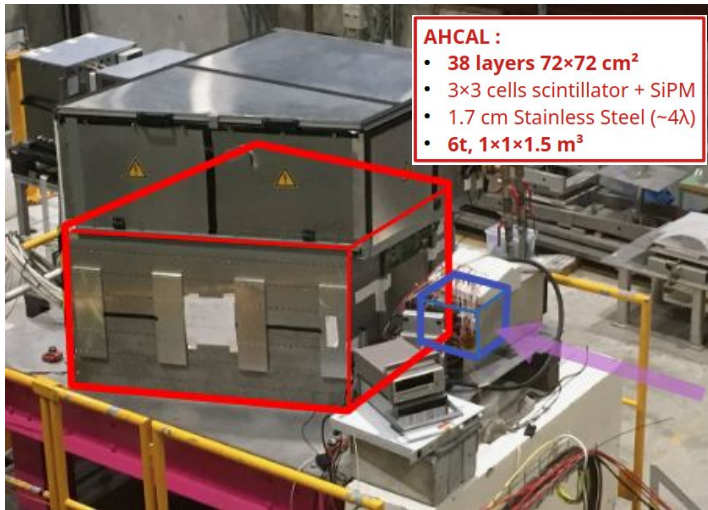
While waiting for the correct  
file to be created

Read the "event"  
(change in directory)

Check of any of the events  
read in this instance are the  
creation of the desired file

Variable storing  
file name

- After last year's meeting: approached by Jiří Kvasnička
  - Offered CALICE AHCAL test beam data to test monitoring with
  - Provided with AHCAL Reader to emulate data taking



courtesy: [Vincent Boudry](#)

corrygeo.geo

```
[AHCAL_0]
material_budget=0.1
number_of_pixels = 24,24
orientation_mode = "xyz"
pixel_pitch = 30.15mm,30.15mm
position=0,0,1746mm
spatial_resolution = 31mm,31mm
role=dut, reference
type="CaliceObject"
time_resolution = 230us

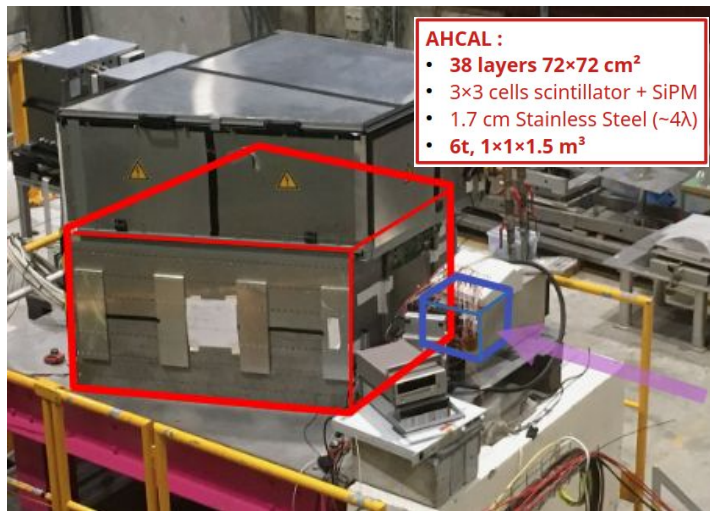
[AHCAL_1]
material_budget=0.1
number_of_pixels = 24,24
orientation_mode = "xyz"
pixel_pitch = 30.15mm,30.15mm
position=0,0,1766mm
spatial_resolution = 31mm,31mm
role=dut
type="CaliceObject"
time_resolution = 230us

[AHCAL_2]
material_budget=0.1
number_of_pixels = 24,24
orientation_mode = "xyz"
pixel_pitch = 30.15mm,30.15mm
position=0,0,1786mm
spatial_resolution = 31mm,31mm
```

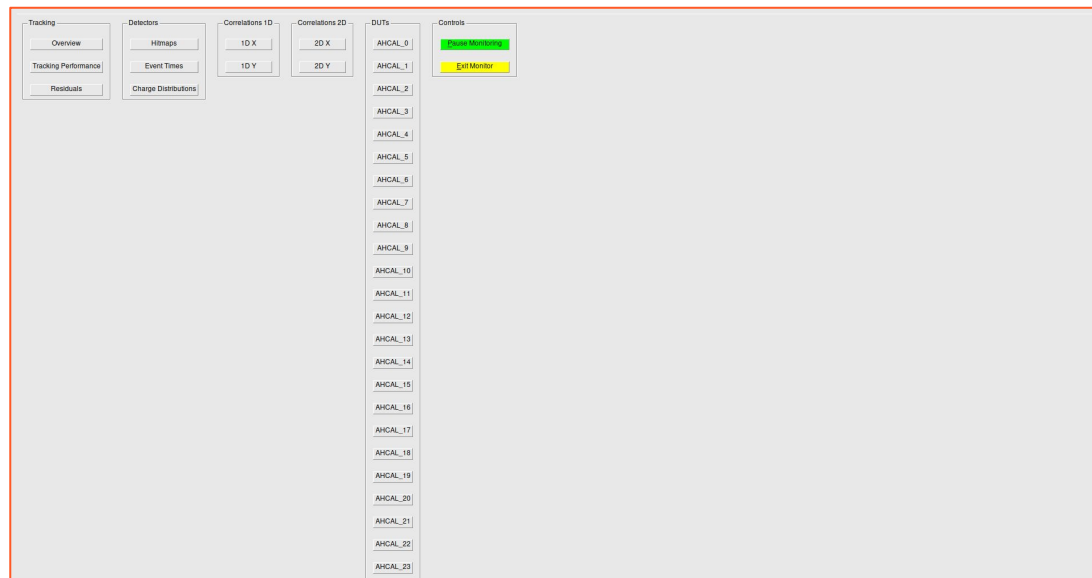


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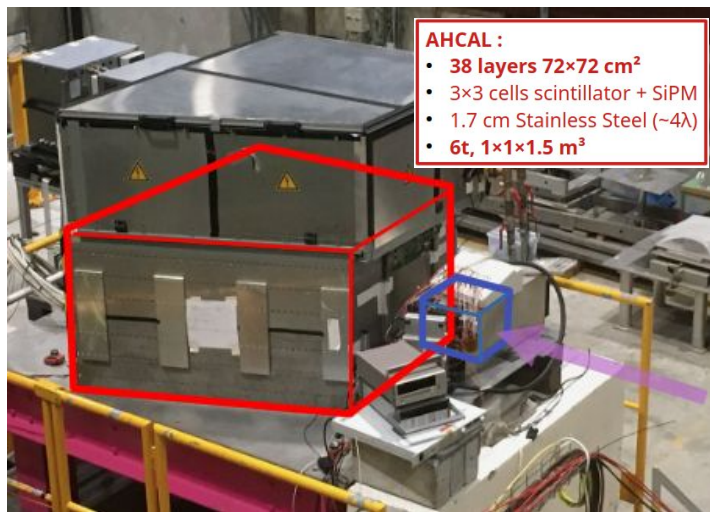
- This is the full window, not enough space for plots
- Not even enough space to fit all layers



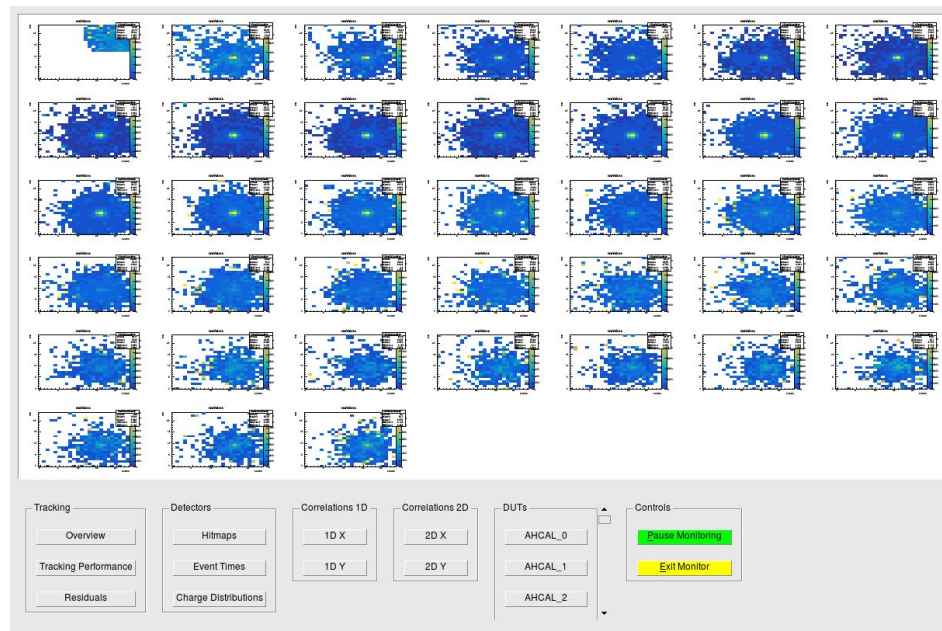
courtesy: [Vincent Boudry](#)



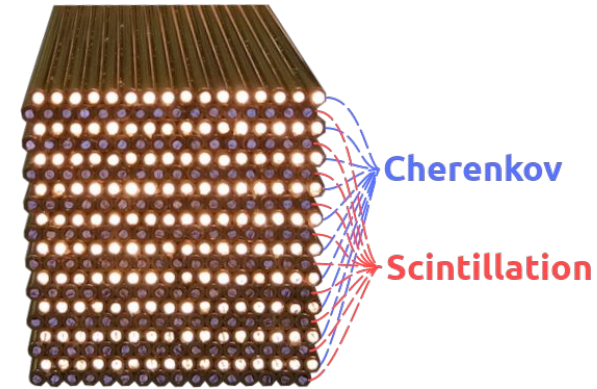
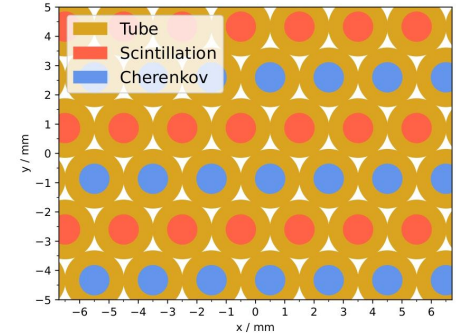
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- Provided with AHCAL Reader to emulate data taking



Vincent Boudry, AIDAInnova 2nd Annual Meeting, 25.04.2023



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- Dual-readout EM prototype
  - 160 Scintillation, 160 Cherenkov individually read out by SiPMs
  - No longitudinal segmentation, i.e. no “layers”
  - But could define Scintillation and Cherenkov channels as own layers or high gain and low gain



courtesy: [INFN-PV Lab](#)